

# A BASIS OF FINITE FEYNMAN INTEGRALS

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based on work with Erik Panzer and Robert M. Schabinger

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# MULTI-LOOP FEYNMAN INTEGRALS

consider  $L$  loop Euclidean Feynman integrals:

$$I = \int \frac{d^d k_1}{i\pi^{d/2}} \cdots \frac{d^d k_L}{i\pi^{d/2}} \frac{1}{D_1^{a_1} \cdots D_N^{a_N}}$$

where  $a_i \in \mathbb{Z}$  and e.g.  $D_1 = k_1^2 - m_1^2$  etc.

**linear dependencies:**

- integration-by-parts (IBP) identities [Tkachov, Chetyrkin '81]
- systematic reduction to small number of master integrals [Laporta '00]
- think of it as linear vector space with some arbitrary basis (master integrals)

**expansion in  $\epsilon = (4 - d)/2$**

- typically sufficient for phenomenological applications
- Laurent coefficients are simpler integrals

**solving methods** typically based on

- 1 direct integration of Feynman (Schwinger) parameter integrals
- 2 differential equations

# AN IMPROVED BASIS FOR FEYNMAN PARAMETERS

consider **Feynman parameter representation** of multi-loop integral


$$I = \frac{\Gamma(\nu - \frac{Ld}{2})(-1)^\nu}{\prod_{i=1}^N \Gamma(\nu_i)} \left[ \prod_{j=1}^N \int_0^\infty dx_j \right] \delta(1 - x_N) \mathcal{U}^{\nu - (L+1)d/2} \mathcal{F}^{-\nu + Ld/2} \prod_{k=1}^N x_k^{\nu_k - 1}$$

where  $\nu = \sum_i \nu_i$ ,  $\nu_i$  denotes propagator multiplicity

presence of **subdivergencies** (= divergencies from Feynman parameter integrations) implies:

- can't directly expand in  $\epsilon$
- no straight-forward analytical or numerical integration

generic approaches to **singularity resolution**:

- 1 sector decomposition [Binoth, Heinrich '00]
- 2 polynomial exponent raising [Tkachov '96, Passarino '00]
- 3 regularising dimension shifts [Panzer '14]
- 4  **basis of finite Feynman integrals** ("dims & dots") [AvM, Schabinger, Panzer '14]

## SECTOR DECOMPOSITION: SHORTCOMINGS

calculate to  $\mathcal{O}(\epsilon)$ :

$$I(\epsilon) = \int_0^1 dt t^{-1-\epsilon} (1-t)^{-1-2\epsilon} {}_2F_1(\epsilon, 1-\epsilon; -\epsilon; t)$$

decompose into sectors: split at (arbitrary)  $t = 1/2$ :

$$I_1(\epsilon) = \int_0^{1/2} dt t^{-1-\epsilon} (1-t)^{-1-2\epsilon} {}_2F_1(\epsilon, 1-\epsilon; -\epsilon; t)$$

$$I_2(\epsilon) = \int_{1/2}^1 dt t^{-1-\epsilon} (1-t)^{-1-2\epsilon} {}_2F_1(\epsilon, 1-\epsilon; -\epsilon; t).$$

rescale, expand in plus distributions, evaluate:

$$I_1(\epsilon) = -\frac{1}{\epsilon} - 1 + \left(3 + \frac{1}{3}\pi^2 - 8\ln(2)\right) \epsilon + \mathcal{O}(\epsilon^2)$$

$$I_2(\epsilon) = -\frac{1}{3\epsilon} + \frac{7}{3} + \left(-7 + \frac{1}{3}\pi^2 + 8\ln(2)\right) \epsilon + \mathcal{O}(\epsilon^2).$$

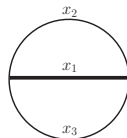
result:

$$I(\epsilon) = -\frac{4}{3\epsilon} + \frac{4}{3} + \left(-4 + \frac{2}{3}\pi^2\right) \epsilon + \mathcal{O}(\epsilon^2).$$

note:

- split up of domain introduces **spurious terms**  $\ln(2)$
- spurious order 5 polynomial denominators: [AvM, Schabinger, Zhu '13]
- destroys linear reducibility & prevents **analytical integration** a la [Brown '08; Panzer '14]

## AN EXAMPLE FOR SUBDIVERGENCIES




$$= \int \frac{d^d k_1}{i\pi^{d/2}} \int \frac{d^d k_2}{i\pi^{d/2}} \frac{1}{((k_1 + k_2)^2 - m^2) k_1^2 k_2^2}$$

$$= -\Gamma(-1 + 2\epsilon) \int_0^\infty dx_1 \delta(1 - x_1) \int_0^\infty dx_2 \int_0^\infty dx_3 \mathcal{U}^{-3+3\epsilon} \mathcal{F}^{1-2\epsilon},$$

with Symanzik polynomials

$$\mathcal{U} = x_1 x_2 + x_1 x_3 + x_2 x_3 \quad \text{and} \quad \mathcal{F} = m^2 x_1 \mathcal{U}.$$

- can't expand integrand in  $\epsilon$ :



$$= - (m^2)^{1-2\epsilon} \frac{\Gamma(-1 + 2\epsilon) \Gamma(\epsilon) \Gamma(1 - \epsilon)}{1 - \epsilon}$$

$\Gamma(\epsilon)$  signals subdivergence

- **Euclidean** integrals: all divergencies from integration **boundaries**
- notation here: restrict to one or several parameters approaching **zero** (not infinity)

# SYSTEMATIC RECOGNITION OF SUBDIVERGENCIES

- follow [Panzer '14]
- consider subsets

$$\{x_1, x_2\}, \quad \{x_1, x_3\}, \quad \{x_2, x_3\}, \quad \{x_1\}, \quad \{x_2\}, \quad \{x_3\}$$

- for each subset  $J$  consider **scaling with  $\lambda$** :

$$J \rightarrow \lambda J$$

for integrand  $P \equiv \mathcal{U}^{-3+3\epsilon} \mathcal{F}^{1-2\epsilon}$ :

$$P \rightarrow P_{J_\lambda} = \lambda^{\deg_J(P)} \tilde{P} \quad \text{where} \quad \lim_{\lambda \rightarrow 0} \tilde{P} = \mathcal{O}(\lambda^0)$$

and the integral measure

$$\prod_{i=1}^3 dx_i \rightarrow \lambda^{|J|} \prod_{i=1}^3 dx_i$$

and read off:

## convergence index

$$\omega_J(P) = |J| + \deg_J(P),$$

$$\lim_{\epsilon \rightarrow 0} \omega_J(P) \leq 0 \quad \Leftrightarrow \quad \text{presence of non-integrable subdivergence}$$

# PANZER'S REGULARISING SHIFT

integrand can be regularized by dimension-shifts [Panzer '14]:

- 1 pick  $J$  for which  $\lim_{\epsilon \rightarrow 0} \omega_J(P) \leq 0$
- 2 multiply by  $1 = \int_0^\infty d\lambda \delta(\lambda - x_J)$  with  $x_J = \sum_{j \in J} x_j$
- 3 rescale  $x_j \rightarrow \lambda x_j$  for all  $j \in J$  and perform partial integration (surface term vanishes)
- 4 new integrand

$$P' = - \frac{1}{\omega_J(P)} \frac{\partial}{\partial \lambda} \tilde{P} \Big|_{\lambda \rightarrow 1}.$$

has improved convergence by design

- 5 iterate until no subdivergencies

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applicability in practice:

- problem: proliferation of terms
- solution: integration by parts (IBP) reductions



# OUR PROPOSAL: MINIMAL DIMS & DOTS

decompose wrt **quasi-finite basis**

$$\begin{aligned}
 & \text{Diagram 1}^{(4-2\epsilon)} = \frac{4(1-\epsilon)(3-4\epsilon)(1-4\epsilon)}{\epsilon s^2} \text{Diagram 2}^{(6-2\epsilon)} \\
 & - \frac{10-65\epsilon+131\epsilon^2-74\epsilon^3}{\epsilon^3 s^2} \text{Diagram 3}^{(6-2\epsilon)} \\
 & - \frac{14-119\epsilon+355\epsilon^2-420\epsilon^3+172\epsilon^4}{(1-2\epsilon)\epsilon^3 s^3} \text{Diagram 4}^{(4-2\epsilon)}
 \end{aligned}$$

basis consists of standard Feynman integrals, but

- in **shifted dimensions**
- with additional **dots** (propagators taken to higher powers)
- old reg. shifts generated  $\mathcal{O}(10\text{MB})$ , here: 3 lines ! (more severe at higher loops)

## EXISTENCE OF QUASI-FINITE BASIS

- 1 start with some basis  $B$  for topology and subtopologies
- 2 assume master  $b$  not quasi-finite and has integrand

$$P = \mathcal{U}^{\nu-(L+1)d/2} \mathcal{F}^{-\nu+Ld/2} \prod_{j=1}^N x_j^{\nu_j-1}, \quad \text{where } \nu = \sum_{i=1}^N \nu_i$$

- 3 consider regularizing dimension shift:

$$P' = -\frac{1}{\omega_J(P)} \prod_{j=1}^N x_j^{\nu_j-1} \left\{ \left( \nu - \frac{(L+1)d}{2} \right) \mathcal{U}^{(\nu+L)-(L+1)(d+2)/2} \mathcal{F}^{-(\nu+L)+L(d+2)/2} \frac{\partial \tilde{\mathcal{U}}}{\partial \lambda} \Big|_{\lambda \rightarrow 1} \right. \\ \left. + \mathcal{F} \text{ derivative term} \right\},$$

$$\text{with } \mathcal{U}_{J_\lambda} = \lambda^{\deg_J(\mathcal{U})} \tilde{\mathcal{U}}$$

- 4 picking any monomial from  $\frac{\partial \tilde{\mathcal{U}}}{\partial \lambda} \Big|_{\lambda \rightarrow 1}$  or  $\frac{\partial \tilde{\mathcal{F}}}{\partial \lambda} \Big|_{\lambda \rightarrow 1}$  gives

**dimension-shifted** and **dotted** integral with **improved convergence** !

- 5 choose one term such that new integral  $b'$  is independent of  $B \setminus b$
- 6 replace  $b \rightarrow b'$  and iterate until  $B$  free of subdivergences (quasi-finite)
- 7 optional: transition quasi-finite  $\rightarrow$  finite integrals

# PRACTICAL ALGORITHM FOR BASIS CONSTRUCTION

given the existence proof, forget about previous construction and just do:

## ALGORITHM: CONSTRUCTION OF (QUASI-)FINITE BASIS

- systematic scan for (quasi-)finite integrals with dim-shifts and dots
- IBP + dimensional recurrence for actual basis change

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### remarks:

- computationally expensive part shifted to IBP solver (Fire, Reduze, LiteRed)
- efficient, easy to automate (implemented in dev. version of Reduze 2)
- any dim-shift good, e.g. shifts by [Tarasov '96], [Lee '10]
- see [Bern, Dixon, Kosower '93] for dim-shifted one-loop pentagon

# EXAMPLE 1A: NON-PLANAR TWO-LOOP VERTEX (QUASI-FINITE)

$$\begin{aligned}
 & \text{Diagram 1} \quad (4-2\epsilon) = \text{Diagram 2} \quad (4-2\epsilon), \\
 & \text{Diagram 3} \quad (4-2\epsilon) = \frac{2-3\epsilon}{\epsilon} \text{Diagram 4} \quad (6-2\epsilon), \\
 & \text{Diagram 5} \quad (4-2\epsilon) = \frac{4(1-\epsilon)(3-4\epsilon)(1-4\epsilon)}{\epsilon^2 s^2} \text{Diagram 6} \quad (6-2\epsilon) \\
 & \quad - \frac{10-65\epsilon+131\epsilon^2-74\epsilon^3}{\epsilon^3 s^2} \text{Diagram 7} \quad (6-2\epsilon) \\
 & \quad - \frac{14-119\epsilon+355\epsilon^2-420\epsilon^3+172\epsilon^4}{(1-2\epsilon)\epsilon^3 s^3} \text{Diagram 8} \quad (4-2\epsilon).
 \end{aligned}$$

# EXAMPLE 1B: NON-PLANAR TWO-LOOP VERTEX (FINITE)

$$\begin{aligned}
 & \text{Diagram 1}^{(4-2\epsilon)} = -\frac{4s^2}{\epsilon(1-2\epsilon)} \text{Diagram 2}^{(8-2\epsilon)}, \\
 & \text{Diagram 3}^{(4-2\epsilon)} = \frac{2(2-3\epsilon)s}{\epsilon^2} \text{Diagram 4}^{(8-2\epsilon)}, \\
 & \text{Diagram 5}^{(4-2\epsilon)} = -\frac{4(1-\epsilon)(1-4\epsilon)}{\epsilon s} \text{Diagram 6}^{(6-2\epsilon)} \\
 & \quad - \frac{2(2-3\epsilon)(5-21\epsilon+14\epsilon^2)}{\epsilon^4 s} \text{Diagram 7}^{(8-2\epsilon)} \\
 & \quad + \frac{4(2-3\epsilon)(7-31\epsilon+26\epsilon^2)}{\epsilon^4(1-2\epsilon)s} \text{Diagram 8}^{(8-2\epsilon)}.
 \end{aligned}$$

## EXAMPLE 2: MASSLESS PLANAR DOUBLE BOX FAMILY

$$b_1 = \text{Diagram} \quad (6-2\epsilon)$$

$$b_2 = \text{Diagram} \quad (6-2\epsilon)$$

$$b_3 = \text{Diagram} \quad (6-2\epsilon)$$

$$b_4 = \text{Diagram} \quad (6-2\epsilon)$$

$$b_5 = \text{Diagram} \quad (6-2\epsilon)$$

$$b_6 = \text{Diagram} \quad (4-2\epsilon)$$

$$b_7 = \text{Diagram} \quad (4-2\epsilon)$$

$$b_8 = \text{Diagram} \quad (6-2\epsilon)$$

## EXAMPLE 3: THREE-LOOP FORM FACTOR

- massless quark and gluon form factors:
  - ▶ simplest objects to study IR properties of QCD
- master integrals:
  - ▶ [Gehrmann, Heinrich, Huber, Studerus '06]
  - ▶ [Heinrich, Huber, Maître '07]
  - ▶ [Heinrich, Huber, Kosower, V. Smirnov '09]
  - ▶ [Lee, A. Smirnov, V. Smirnov '10]
  - ▶ [Baikov, Chetyrkin, A. Smirnov, V. Smirnov, Steinhauser '09]
  - ▶ [Lee, V. Smirnov '10]  $\Leftarrow$  the only complete weight 8
  - ▶ [Henn, A. Smirnov, V. Smirnov '14] (diff. eqns.)
- form factor @ 3-loops:
  - ▶ [Baikov, Chetyrkin, A. Smirnov, V. Smirnov, Steinhauser '09]
  - ▶ [Gehrmann, Glover, Huber, Iziklerli, Studerus '10, '10]



### EXAMPLE 3: THREE-LOOP FORM FACTOR [AVM, PANZER, SCHABINGER; TO APPEAR]

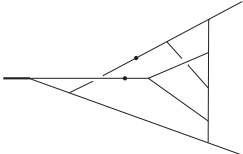
$$F_3^q = \frac{1}{\epsilon^6} \left[ c_1 \text{ (10-2}\epsilon) + c_2 \text{ (8-2}\epsilon) + c_3 \text{ (10-2}\epsilon) + c_4 \text{ (6-2}\epsilon) + c_5 \text{ (10-2}\epsilon) \right. \\
 + c_6 \text{ (10-2}\epsilon) + c_7 \text{ (8-2}\epsilon) + c_8 \text{ (6-2}\epsilon) \left. \right] + \frac{1}{\epsilon^4} \left[ c_9 \text{ (6-2}\epsilon) \right] \\
 + \frac{1}{\epsilon^3} \left[ c_{10} \text{ (6-2}\epsilon) + c_{11} \text{ (6-2}\epsilon) + c_{12} \text{ (8-2}\epsilon) + c_{13} \text{ (8-2}\epsilon) + c_{14} \text{ (6-2}\epsilon) \right. \\
 + c_{15} \text{ (8-2}\epsilon) \left. \right] + \frac{1}{\epsilon^2} \left[ c_{16} \text{ (6-2}\epsilon) \right] + \frac{1}{\epsilon^1} \left[ c_{17} \text{ (6-2}\epsilon) + c_{18} \text{ (6-2}\epsilon) \right. \\
 \left. + c_{19} \text{ (6-2}\epsilon) + c_{20} \text{ (4-2}\epsilon) + c_{21} \text{ (4-2}\epsilon) + c_{22} \text{ (6-2}\epsilon) \right]$$

## EXAMPLE 4: FOUR-LOOP FORM FACTOR [AvM, PANZER, SCHABINGER; IN PROGRESS]

- example: a non-planar 12-line top level topology @ 4-loops

- analytical result with HypInt [Panzer]:

(6-2 $\epsilon$ )


$$= \frac{18}{5} \zeta_2^2 \zeta_3 - 5 \zeta_2 \zeta_5 + \mathcal{O}(\epsilon) \quad \approx 3.18074 + \mathcal{O}(\epsilon)$$

- numerical result with Fiesta [A. Smirnov]:  $3.18082 + \epsilon 58.8288 + \mathcal{O}(\epsilon^2)$

**advantages** of (quasi-)finite basis:

- straight-forward to integrate numerically (in principle)
- no blow up in number of numerical integrations (speed, stability)
- no cancellation of spurious structures (stability)

**experiments** with numerical evaluations:

- naive straight-forward implementation works already quite well
- convenient: employ existing sector decomposition programs  
Fiesta, SecDec and `sector_decomposition`
- (quasi-)finite integrals: faster & more reliable

# CONCLUSIONS

## basis of finite integrals (dims and dots):

- simple and efficient method for singularity resolution in multi-loop integrals
- analytical integrations: quasi-finite integrals are Feynman integrals (dim-shifted, dotted)
- numerical integrations: faster and more stable evaluations

## results and outlook:

- massless form factors @ 3-loops: first independent rederivation at heigher weights
- massless form factors @ 4-loops: cusp anomalous dimension and more (in progress)
- phase space integrals (outlook)